

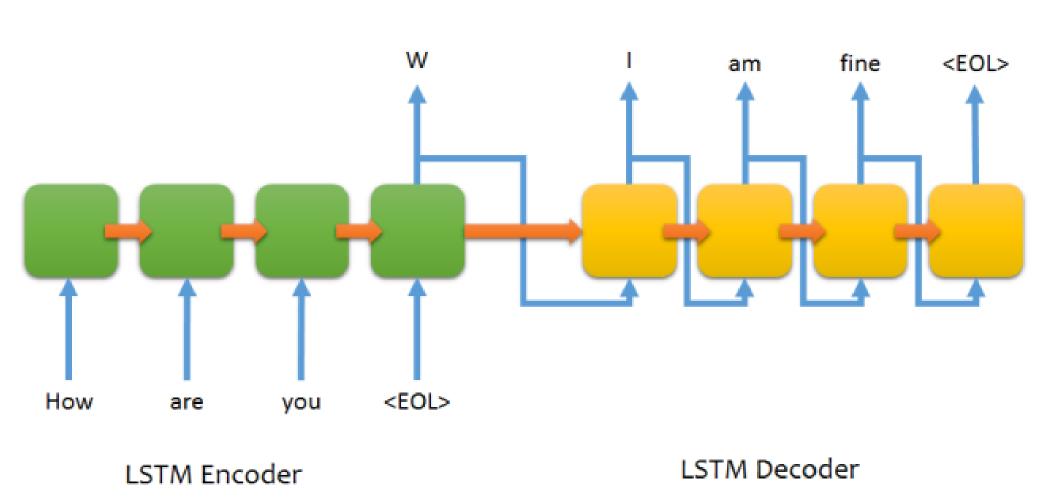


### Objectives

- Augment a trained Seq2Seq [1] model with online Active Learning.
- Leverage a novel human-in-the-loop feedback mechanism to generate more coherent, interesting, relevant and engaging responses.
- Use active learning as a form of reinforcement: eliminate the need for hand-crafted reward functions.

## State of the Art

LSTM Encoder-Decoder architectures like Seq2Seq [1] are known to generate linguistically robust but dull, short and generic responses (Figure 2).





me: Hello? bot: Hi. me: How are you? bot: I'm fine. • me: What's your name? bot: It's hard to describe. •me: How so? bot: I'm not sure. • me: Are you intelligent? bot: Yes, well... • me: What are you? bot: I'm not sure. • me: Do you plan on taking over the world? bot: No, i don't.

# **Deep Active Learning for Dialogue Generation**

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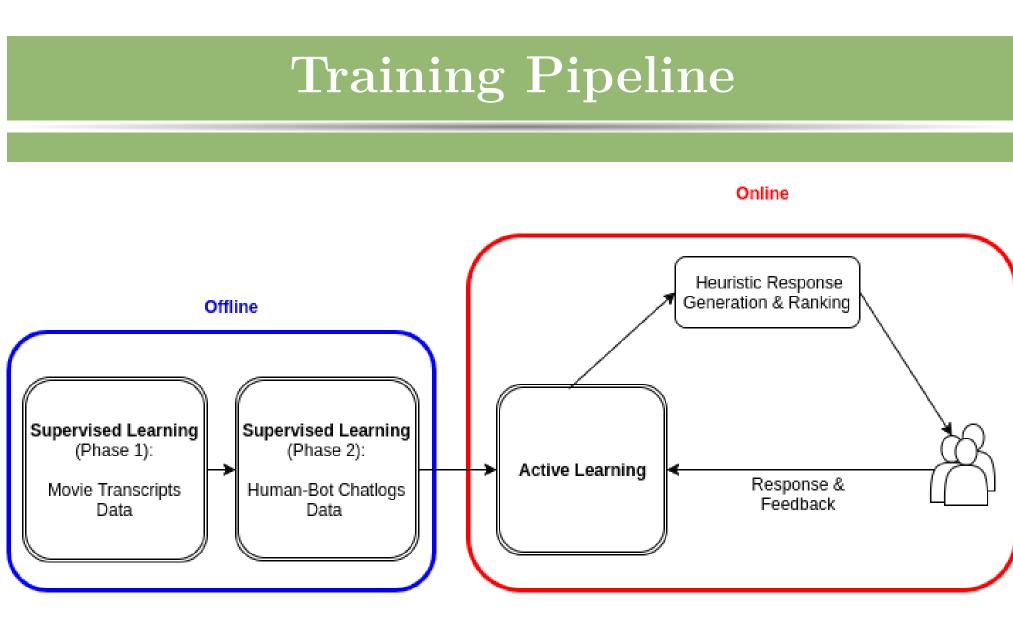


Figure 3: Proposed Training Architecture

We go through three training phases for the Seq2Seq model (one encoder layer and one decoder layer with 300 hidden LSTM units each):

**Phase 1:** Offline SL. Generic dataset (300K pairs) of movie dialogues.

**Phase 2:** Offline SL. Fine-tuning on a second dataset (8K pairs) of human-Jabberwacky bot chatlogs.

**Phase 3:** Online AL with a human trainer.

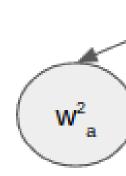
#### Online Active Learning

```
I don't want to work today.
     No, you've just got to be quick.
       wish i could robot.
     Ok i lie.
     Aww :).
     Why not?
feedback:
         just want to lie in my bed and have pizza.
      Good idea.
     Does he...
     I can't do that again!
bot: Ok.
bot: Why not?
feedback: Good idea, may I join you?
human: I don't want to work today.
bot: Why not?
bot: Ok.
bot: I wish I could.
bot: No, you've just got to be quick.
bot: Aww :).
feedback:
human: I just want to lie in bed and have pizza.
bot: Good idea, may I join you?
     I can't do that again!
     Good idea.
bot:
bot: Ok.
     Does he?
bot:
. . . . . .
```

Figure 4: Human-in-the-Loop Feedback Mechanism.



the beams.



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#### Heuristic Response Generation

We use hamming-diverse Beam Search [2] to generate Kresponses at each turn. The beams are diversified by maximizing an objective that consists of a standard sequence likelihood term and a dissimilarity metric between

**Beam Search:** Likely to produce almost identical beams like "I don't care!" and "I don't care.".

**Diverse Beam Search:** Likely to produce beams like "I don't care!" and "Who cares?".

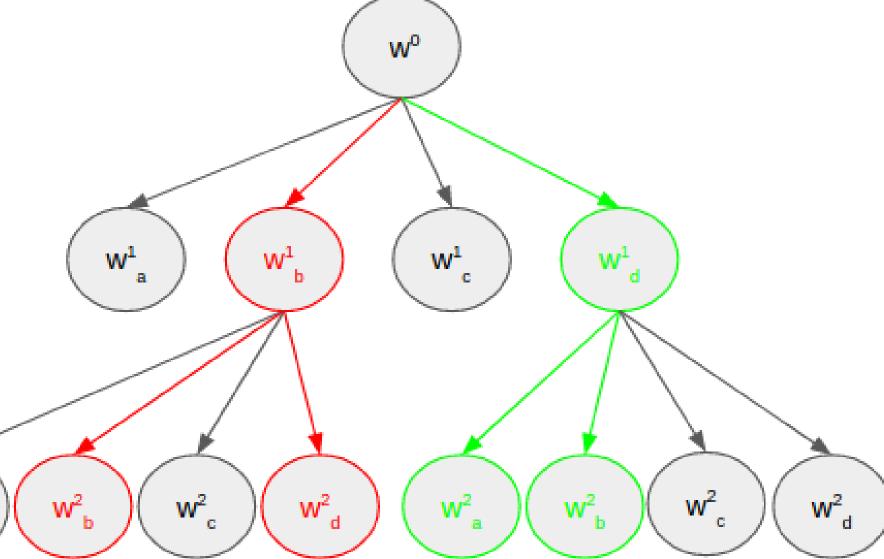


Figure 5: Beam Search (both red or both green) vs. Diverse Beam Search (one red and one green).

#### User Study

cs like BLEU, ROUGE, WER and NIST are suitable achine translation evaluation, but not for response y evaluation in dialogue.

**ne Training:** One human trained the model with rompts of his choice.

**Prompts:** We randomly selected 100 of those and stically rephrased them. Thus, "How's it going" ltered to "How are you doing?", "I hate you." to *n't like you!"*, etc.

**Pairs:** We collected the responses of three models SL2 and SL2+oAL to the test prompts.

uation: We asked 5 human judges to rate the test on 4 axes: Syntactic Coherence, Relevance to Prompt, Interestingness and User Engagement.

Avg.

[1] Sutskever et al.

[2] Vijayakumar et al. sequence models.



#### **Experimental Evaluation**

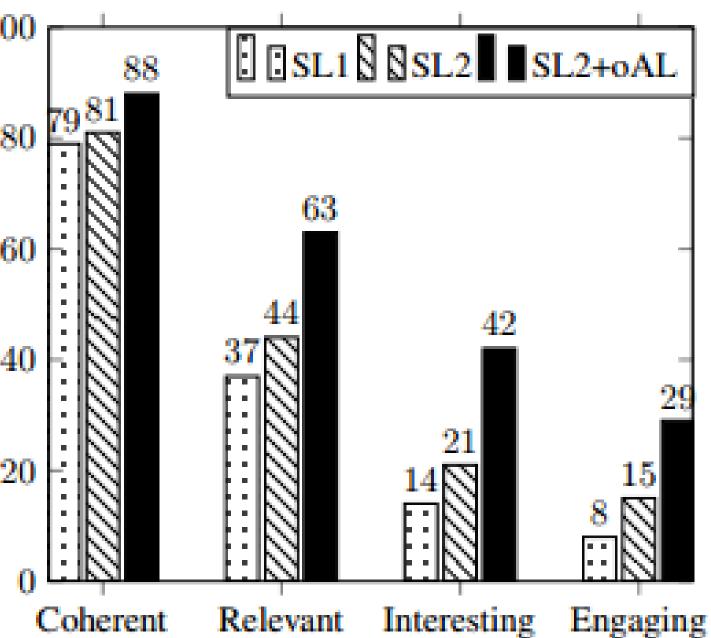
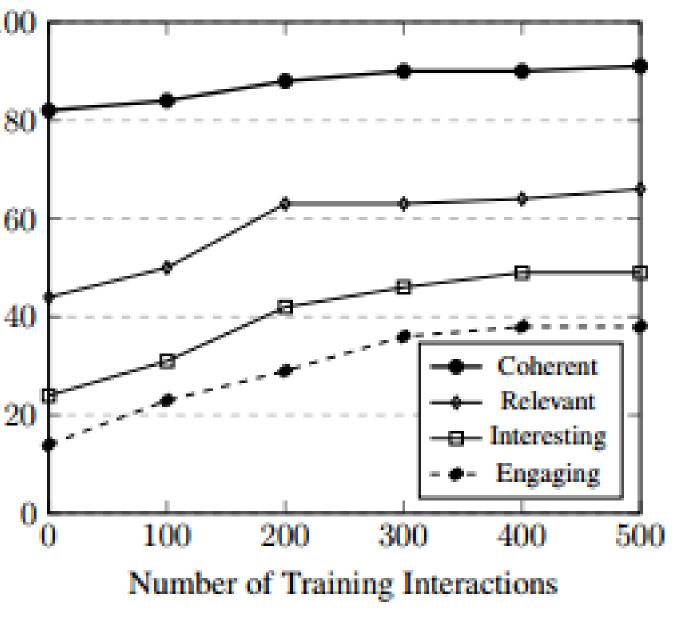
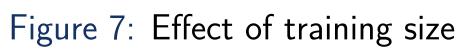


Figure 6: Model comparison





#### References

- Sequence to sequence learning with neural networks. In *NIPS*, pages 3104–3112, 2014.
- Diverse beam search: Decoding diverse solutions from neural
- *arXiv preprint arXiv:1610.02424*, 2016.